

FSM Inference from Long Traces

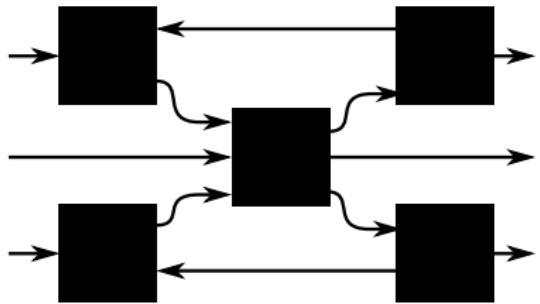
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Computer Research Institute of Montréal (Canada)

FM 2018 - 15 July 2018

Context

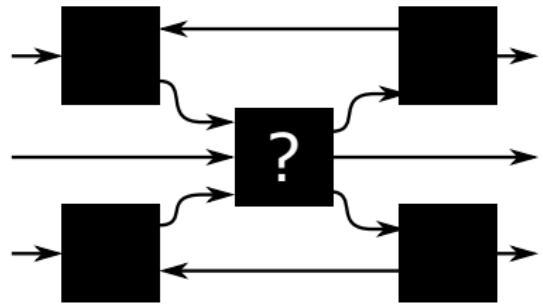
Increasingly modular applications



Context

Increasingly modular applications

- ⇒ no source code
- ⇒ no documentation

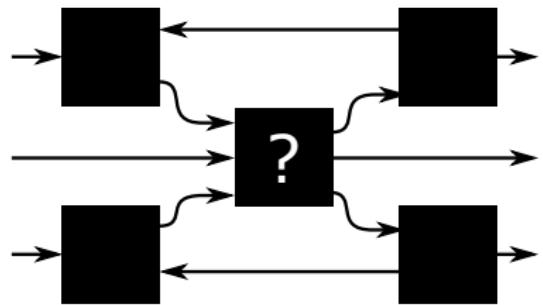


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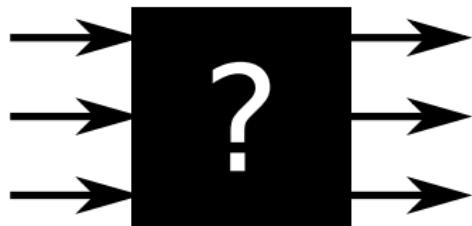
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Can we trust these modules?

Problematic

"Black Box"



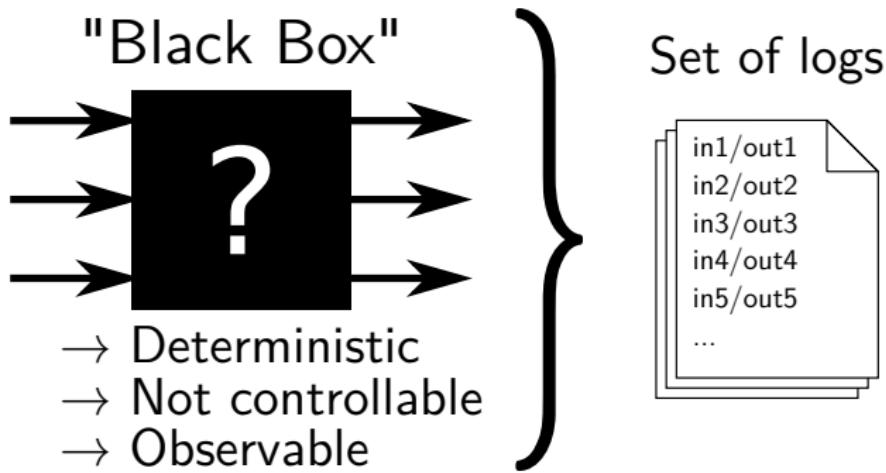
Problematic

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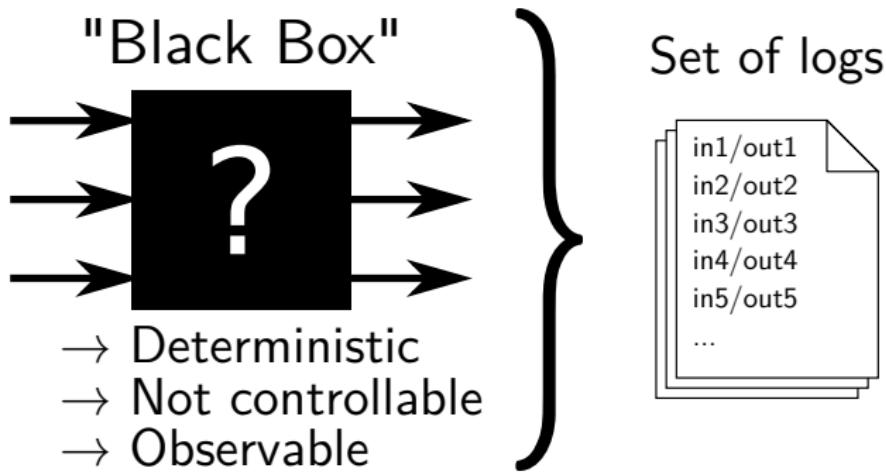


- Deterministic
- Not controllable
- Observable

Problematic



Problematic



Question: How can we infer a model for the black box from long traces?

Overview

- 1 Introduction
- 2 Passive Inference
- 3 Incremental Inference
- 4 Conclusion

Overview

1 Introduction

2 Passive Inference

3 Incremental Inference

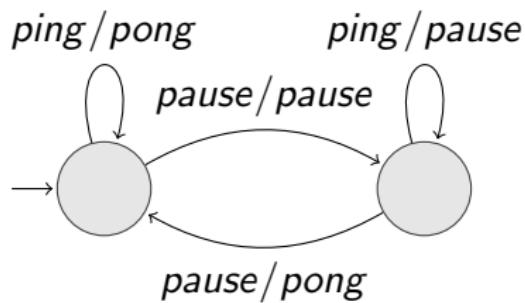
4 Conclusion

Model

Finite State Machine (FSM)

A FSM is a 5-tuple (S, s_0, I, O, T) , where:

- S is a finite set of states with initial state s_0
- I and O are finite non-empty sets of inputs and outputs
- T is a transition relation $T \subseteq S \times I \times O \times S$



Law of parsimony: Among competing hypotheses, the one with the fewest assumptions should be selected

For FSM inference: Find a *minimal* FSM consistent with the set of traces

Formal statement of the problem

Let \mathcal{T} be a set of traces and n be an integer. Find an FSM with at most n states consistent with \mathcal{T}

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CSP formulation (Biermann & Feldman 1972)

The set of states Q is represented by integer variables $q_0, q_1, \dots, q_{|Q|-1}$ taking values from 0 to $n - 1$ such that:

$$\begin{aligned} \forall q_i, q_j \in Q : & \text{ if } q_i \not\geq q_j \text{ then } q_i \neq q_j \\ & \text{if } \exists a \in I : \lambda(q_i, a) = \lambda(q_j, a) \text{ then} \\ & (q_i = q_j) \Rightarrow (\Delta(q_i, a) = \Delta(q_j, a)) \end{aligned}$$

Efficient SAT formulation (Heule & Verwer 2013)

Translate a CSP formulation to SAT using unary coding for each integer variable, auxiliary variables and breaking symmetry formula

Problem: The time required to infer a model increases exponentially with the size of the logs

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Idea: Do not consider the entire logs

First method: Use log prefixes and incrementally grow them

Algorithm 1 Infer an FSM from a set of traces

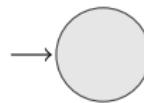
Input: A set of traces \mathcal{T} and an integer n

Output: An FSM with at most n states and consistent with \mathcal{T} if it exists

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1:  $C := \emptyset$ 
2: while  $C$  is satisfiable do
3:   Let  $M$  be an FSM of a solution of  $C$ 
4:   if  $\mathcal{T} \subseteq Tr_M$  then
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9: end while
10: return false
```

Example

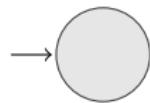
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$$\boxed{\omega = \epsilon}$$

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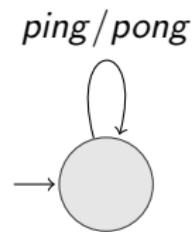
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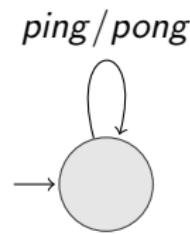
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$$\omega = \text{ping/pong}$$

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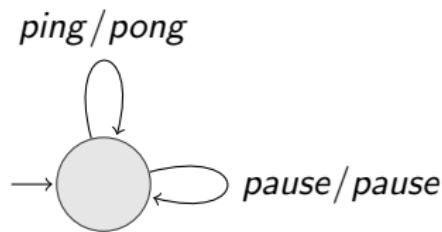
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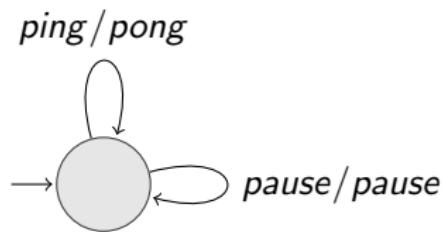
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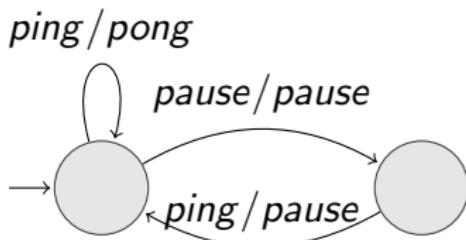
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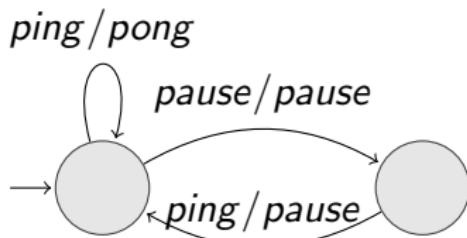
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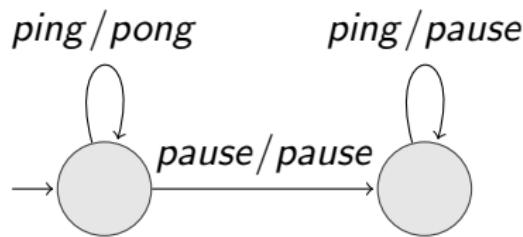
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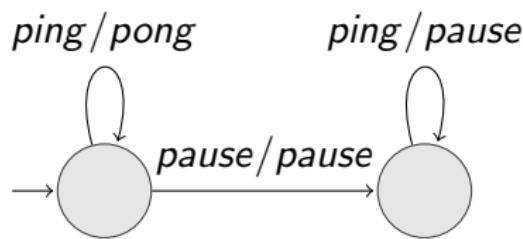
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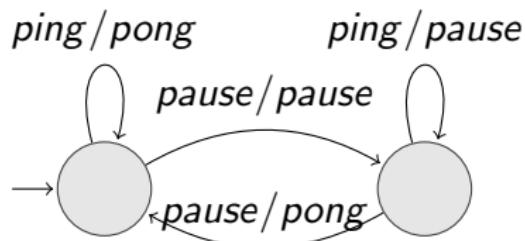
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Example

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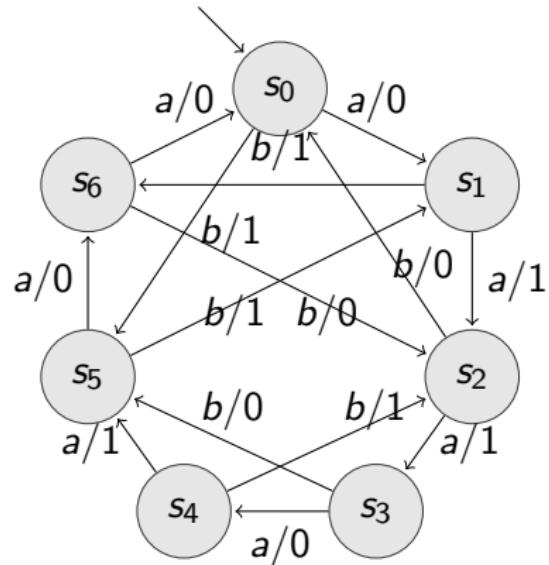


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Benchmark

We calculate the average time over ten instances used to infer a random FSMs with seven states, two inputs a and b , and two outputs 0 and 1

Trace length	H&V method (sec.)	Prefix method (sec.)
1k	2.5	0.2
2k	7.3	0.2
4k	20	0.2
8k	53	0.2
16k	190	0.3
32k	Out of Memory	0.5
64k	Out of Memory	1.5



Example of a random FSM

Infrequent Events

Algorithm 2 Example client

```
1: while true do
2:   if rand() mod 1/p == 0 then
3:     send("pause");
4:   else
5:     send("ping");
6:   end if
7: end while
```

$\mathcal{T} = \text{ping/pong}.\text{ping/pong}.\text{ping/pong}.\text{ping/pong}.\text{ping/pong}...$
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Infrequent Events

We vary the chances that b will appear in a 64 000 length trace produced by a randomly generated FSM

Probability of b	Prefix-based (sec.)
50 %	1.5
25 %	1.4
10 %	1.4
1 %	3.5
0.5 %	6.0
0.3 %	16
0.2 %	90
0.1 %	Out of Memory

Infrequent Events

Idea: Add less strong constraints that refute the conjectures

Method: Let M be a conjecture and ω be the shortest trace in $\mathcal{T} \setminus Tr_M$. If there exists a suffix ω' of ω such that $\forall s : \omega' \notin Tr(s)$ then it's sufficient to add the constraint that $\exists s : \omega' \in Tr(s)$ to refute M

Observations:

- The length of ω' can be much shorter than the length of ω
- The constraint $\exists s : \omega' \in Tr(s)$ is easy to write in SAT

Algorithm 3 Infer an FSM from a set of traces

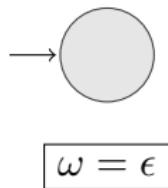
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8:   if  $\exists \omega'$  the shortest suffix of  $\omega$  such that  $\forall s : \omega' \notin Tr(s)$  then
9:      $C := C \wedge C'_\omega$ , where  $C'_\omega$  has clauses encoding the fact that  $\exists s : \omega' \in Tr(s)$ 
10:    else
11:       $C := C \wedge C_\omega$ , where  $C_\omega$  has clauses encoding the fact that  $\omega \in Tr_M$ 
12:    end if
13:  end while
14: return false
```

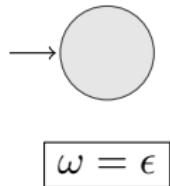
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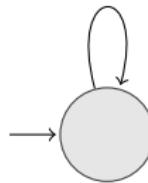
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ping/pong

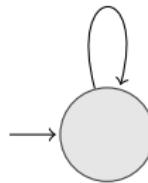


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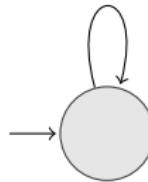


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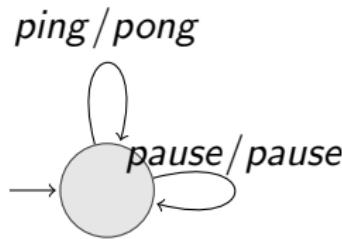
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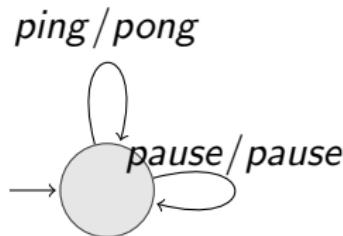
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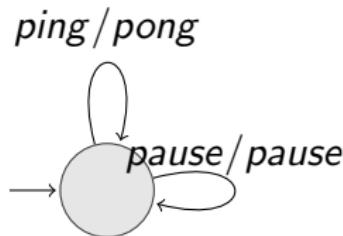
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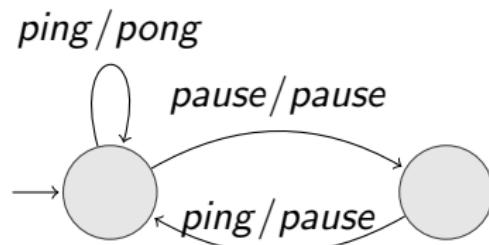
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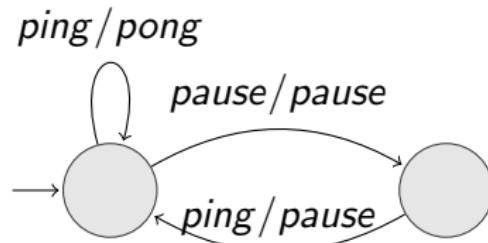
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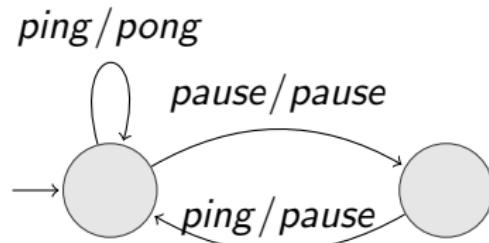
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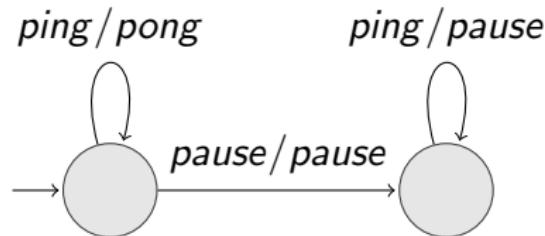
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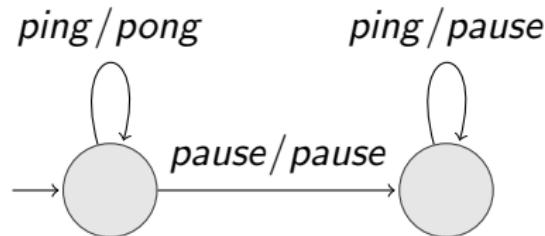
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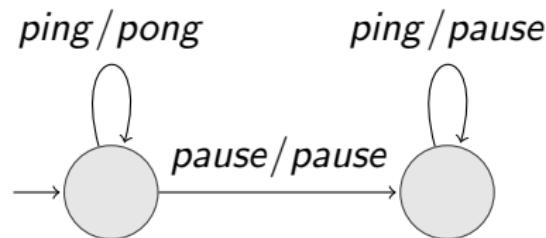
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$\omega = \text{ping/pong}, \omega' = \text{pause/pause}, \omega'' = \text{ping/pause.ping/pause}$

Example

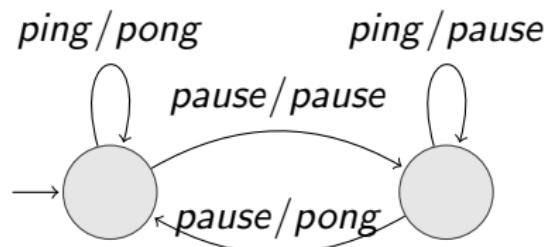
$T = \text{ping/pong}.\text{ping/pong}.\text{ping/pong}.\text{ping/pong}.\text{ping/pong}...\text{ping/pong}.\text{pause/pause}.\text{ping/pong}.\text{ping/pong}...\text{ping/pong}.\text{pause/pause}.\text{ping/pong}.\text{ping/pong}...\text{ping/pong}.\text{pause/pause}.\text{ping/pong}.\text{ping/pong}...\text{ping/pong}.$



$\omega = \text{ping/pong}, \omega' = \text{pause/pause}, \omega'' = \text{ping/pong}.\text{ping/pong}$

Example

$T = \text{ping/pong}.\text{ping/pong}.\text{ping/pong}.\text{ping/pong}.\text{ping/pong}.\text{ping/pong}...$
 $\dots \text{ping/pong}.\textbf{pause/pause}.\text{ping/pong}.\text{ping/pong}.\text{ping/pong}...\text{ping/pong}.$
 $\dots \text{ping/pong}.\textbf{pause/pong}.\text{ping/pong}.\text{ping/pong}.\text{ping/pong}...$



$$\omega = \text{ping/pong}, \omega' = \text{pause/pause}, \omega' = \text{ping/pause}.\text{ping/pong}, \omega' = \text{pause/pong}$$

Benchmark

We vary the chances that b will appear in a 64000 length trace produced by a randomly generated FSM

Probability of b	Prefix-based (sec.)	Suffix-based (sec.)
50 %	1.5	2.4
25 %	1.4	1.4
10 %	1.4	1.4
1 %	3.5	1.4
0.5 %	6.0	1.5
0.3 %	16	1.4
0.2 %	90	1.5
0.1 %	Out of Memory	1.6

Overview

1 Introduction

2 Passive Inference

3 Incremental Inference

4 Conclusion

Conclusion

Our contributions include incremental algorithms for passive FSM inference

- Prefix-based algorithm
- Suffix-based algorithm

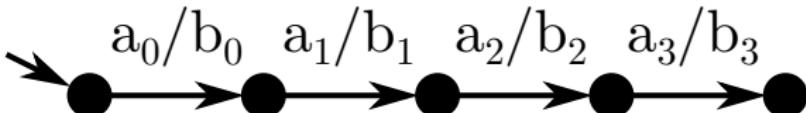
As future work, we want to investigate whether their combination will result in a more efficient method

Thank you

Table 1: Summary for encoding passive inference from ISFSM

$W = (X, x_0, I, O, T)$ into SAT. n is the maximal number of states in an FSM to infer, $B = \{0, \dots, n - 1\}$

Clauses	Range
$v_{x_0,0}$	
$(v_{x,0} \vee v_{x,1} \vee \dots \vee v_{x,n-1})$	$x \in X$
$(\neg v_{x,i} \vee \neg v_{x,j})$	$x \in X; 0 \leq i < j < n$
$(\neg v_{x,i} \vee \neg v_{x',i})$	$x \not\equiv x'; i \in B$
$(y_{a,i,j} \vee \neg v_{x,i} \vee \neg v_{x',j})$	$(x, a, o, x') \in T; i, j \in B$
$(\neg y_{a,i,h} \vee \neg y_{a,i,j})$	$a \in I; h, i, j \in B; h < j$
$(y_{a,i,0} \vee y_{a,i,1} \vee \dots \vee y_{a,i,n-1})$	$a \in I; i \in B$
$(\neg y_{a,i,j} \vee \neg v_{x,i} \vee v_{x',j})$	$(x, a, o, x') \in T; i, j \in B$



$V_{0,0}$	$V_{1,0}$	$V_{2,0}$	$V_{3,0}$	$V_{4,0}$
$V_{0,1}$	$V_{1,1}$	$V_{2,1}$	$V_{3,1}$	$V_{4,1}$
$V_{0,2}$	$V_{1,2}$	$V_{2,2}$	$V_{3,2}$	$V_{4,2}$

Clauses	Range
$v_{x_0,0}$	
$(v_{x,0} \vee v_{x,1} \vee \dots \vee v_{x,n-1})$	$x \in X$
$(\neg v_{x,i} \vee \neg v_{x,j})$	$x \in X; 0 \leq i < j < n$
$(\neg v_{x,i} \vee \neg v_{x',i})$	$x \not\equiv x'; i \in B$
$(v_{x,i} \wedge v_{x',i}) \Rightarrow (v_{\Delta(x,a),j} \Rightarrow v_{\Delta(x',a),j})$	$x, x' \in X \lambda(x, a) = \lambda(x', a); i, j \in B$
